REAL COMMUTATIVE SEMIGROUPS ON THE PLANE. II(1)

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1. In the first note of this title, a study was begun of commutative topological semigroups on the plane E which contain an appropriate copy of the multiplicative semigroup R of all real numbers. Among other things, the product semigroup on $R \times R$ was distinguished from among all such. The main result of this note is to shift commutativity and a part of the assumption concerning R from the hypothesis to the conclusion of various theorems. Thus, in spite of the title, we do not assume commutativity, and the assumption concerning R is considerably weakened. On the other hand, these properties are never far away in our present study. In particular, a characterization of $R \times R$ is given under these weaker conditions.

The assumption which replaces that about R is simply that E contains a zero 0 which belongs to the closure of the component G of the identity of the maximal subgroup H(1). The other assumptions which are necessary for the final result anyway force the presence of a copy of R. Actually even this hypothesis is suspect. We have some reason for thinking that the assumption about square roots of 1 (see the main theorem) leads to the presence of a zero and if H(1) is dense in E there seems to be some hope in showing $0 \in G^-$. We expect to say more about this later.

2. In this section we collect the definition of various symbols and terms and list certain of our assumptions.

First, E will consistently denote a topological semigroup on the plane with zero 0 and identity 1. These elements are characterized by the identities: $1 \cdot x = x \cdot 1 = x$ and $0 \cdot x = x \cdot 0 = 0$ for all $x \in E$. For $x \in E$, we set $x^2 = x \cdot x$ and say that an element x is nilpotent if $x \neq 0$ and $x^2 = 0$ (this requires more than is usually required, but is satisfactory for our purposes). An element x is a square root of 1 if $x^2 = 1$. An element x is an idempotent if $x^2 = x$.

For sets X, $Y \subset E$, X - Y denotes the complement of Y in X, XY denotes the set of all products xy with $x \in X$, $y \in Y$, and X^- denotes the closure of X in E.

By an isomorphism between two topological semigroups S and T is meant a function from S onto T which is both a topological and algebraic isomorphism. Of course, S and T are said to be isomorphic if such an isomorphism exists, a fact which we signify by writing $S \cong T$.

Following the usage in [4] and elsewhere, H(1) denotes the maximal sub-

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group of E, i.e. the set of all x in E which have an inverse with respect to 1. The component of the identity in H(1) is denoted by G and the boundary of G by L. We invariably use R to denote the multiplicative semigroup of all real numbers.

In addition to the above somewhat more natural assumptions about E we now list the following which forms a standing assumption throughout the paper:

E contains no nilpotent elements and 0 belongs to the closure of G.

As we have implied, the joining of these two hypotheses in one does not reflect our feelings about their nature and is done simply for the sake of brevity.

3. This section begins with a statement of the main theorem and then proceeds to establish a number of results, listed as propositions, on which its proof is based. Several of these results are analogous to results in [1] and in some cases we simply indicate the modifications necessary to make proofs there adequate here. The proof of the main theorem is postponed until these propositions are out of the way. The paper concludes with two remarks about the hypotheses (2) and (3).

MAIN THEOREM. Suppose E is a topological semigroup on the plane with zero 0 and identity 1. Assume that $0 \in G^-$ and that E contains no nilpotent elements. Then the following conditions are equivalent:

- (1) $E \cong R \times R$,
- (2) E has exactly four idempotents and 1 has at least three square roots,
- (3) H(1) is dense in E and has at least three components.

According to [4], H(1) and G are Lie groups which are open subsets of the plane and L is an ideal in $G \cup L$. Since G is connected, it is (topologically) the cartesian product of a compact subgroup and a Euclidean space (see [7], for example). If the compact group is nontrivial it is the circle group, G is isomorphic to the multiplicative group of nonzero complex numbers and H(1) = G [3]. If the compact group is trivial then G is topologically a plane and hence is either the two dimensional vector group or the group of affine transformations of the line [6, pp. 258, 238 and 257].

Thus each of conditions (2) and (3) force G to be one of the latter two groups. The possibilities for L in this case were determined in [5]. The only case in which L contains a zero and G^- contains no nilpotent elements is the case in which G (and therefore G^-) is actually commutative, L is a line and $L-\{0\}$ is the union of two groups A and B with $AB=\{0\}$.

According to [2], whenever G is one of the groups on the plane, there is a one-parameter subgroup $P \subset G$ emanating from every right zero in L. Thus under the present circumstances, if either (2) or (3) holds, there exists a one-parameter subgroup $P \subset G$ such that $P^- = P \cup \{0\}$. The argument given in [1] is now adequate with almost no change to show that $G^- \cong P^- \times P^-$. We thus have the following result:

PROPOSITION 1. If either condition (2) or (3) holds then there exists a one-parameter subgroup $P \subseteq G$ with $P^- = P \cup \{0\}$ and G^- is isomorphic to $P^- \times P^-$.

For the remainder of the paper we take a fixed one-parameter subgroup of G having the properties just given. All reference to P is to this subgroup.

PROPOSITION 2. If G^- is isomorphic to $P^- \times P^-$ then H(1) has only a finite numbers of components.

Proof. The proof of this result parallels and uses parts of the proof of the corresponding result in [1]. Suppose H(1) contains an infinite sequence of components C_1, C_2, \cdots . Each C_i has the form x_iG for some $x_i \in H(1)$. Since the boundary L of G is a (closed) topological line and multiplication by x_i is seen to be a homeomorphism on E, each x_iG is topologically a plane whose boundary is a closed topological line. Furthermore, $0 \in (x_i G)^-$ for all i. Let S be a circle with center at 0. Recall that A denotes one of the components of $L-\{0\}$. For each i we can choose a largest point s_i of x_iA so that $x_i \in S$. There is then a point $x \in S$ which is a cluster point of the s_i . It is then not difficult to show, as in [1], that x is also a cluster point for a sequence of points each belonging to some $x_i B$ where B is the other component of $L - \{0\}$. Thus we can construct two sequences of points which we may as well call s_i and t_i so that $s_i \rightarrow x$, $t_i \rightarrow x$, $s_i \in x_i A$ and $t_i \in x_i B$. If we can show that $x_i B = B x_i$ we have $s_i t_i = 0$ for all i since $AB = \{0\}$. Therefore $x^2 = 0$ and we have a nilpotent element, contrary to our standing assumption. Since $x_iG = Gx_i$ we have $x_i L = Lx_i$. The only question then is whether $x_i b = ax_i$ is possible for some $b \in B$, $a \in A$. But if so then $(x_i b)(x_i b) = (x_i b)(ax_i) = x_i(ba)x_i = 0$ which again is contrary to our assumption about nilpotent elements. Thus $x_i B$ $=Bx_i$ and the proof of the proposition is complete.

Assume that G^- is isomorphic to $P^- \times P^-$. By the previous result, H(1) has a finite number of components. Let $C_0 = G$ and let C_1, \dots, C_n denote the remaining components of H(1). Take $x_i \in C_i$; thus $C_i = x_i G$. We now develop some notation and terms for use in the next proposition and again in Proposition 7. This is done in lieu of talking about rays and sectors as was done in [1] in proving that H(1) has at most four components.

Since the components A and B of $L-\{0\}$ are orbits under the action of G, x_iA and x_iB are orbits under the action of G for any x_i . Thus if for any $i, j, (x_iA) \cap (x_jA) \neq \emptyset$ then $x_iA = x_jA$. A similar statement holds for the x_iB . Since $x_iB = Bx_i$, $(x_iA) \cap (x_jB) = \emptyset$ for all i, j. Now each C_i is a closed halfplane which contains 0. If a distinct pair C_i and C_j have a nonzero point in common it is a boundary point and they have an entire edge (either x_iA^- or x_iB^-) in common. Thus E-H(1) is a set which is separated by the omission of zero into n+1 components D_0, \dots, D_n . Furthermore, each set D_i is either a closed half-line or a closed half-plane. Number the C_i in a counterclockwise direction from G and assume that D_i is between C_i and C_{i+1} (in the obvious sense) for $i=0,1,\dots,n-1$, and D_n is between C_n and C_0 . We shall refer to C_1 as the first and C_n as the last component of H(1) after G.

PROPOSITION 3. Suppose $G^- = P^- \times P^-$. If C is either the first or last component of H(1) then there exists $x \in C$ with $x^2 = 1$.

Proof. Let $\chi(x) = x^2$ for $x \in E$. For each i, $\chi(C_i) = C_j$ for some j and j = i if and only if i = 0. Also, since there are no nilpotent elements, $\chi(D_i) \subset D_j$ for each i and some j. Assume $C = C_1$. The argument is similar if $C = C_n$. Now D_0 has a nonzero point in common with L and hence contains one of the components of $L - \{0\}$. Let this component be A. Since $\chi(A) \subset A$, $\chi(D_0) \subset D_0$.

Now $\chi(C)$ must have nonzero boundary points in common with $\chi(D_0)$, $\chi(C)$ is a component of H(1) and $\chi(C) \neq C$. Since $\chi(D_0) \subset D_0$, the only component of H(1) satisfying these conditions is G. Hence $\chi(C) = G$, so there exists $x \in C$ such that $x^2 = 1$.

PROPOSITION 4. Assume $G^- = P^- \times P^-$. If $x^2 = 1$ then x is in the center of E; i.e. xy = yx for all $y \in E$.

Proof. Let g(y) = xyx for $y \in E$. Let F denote the fixed-point set of g, that is, F is the set of y such that g(y) = y. Obviously g is an involution on E so F is either a single point, a closed line or all of E. Now G is a normal subgroup so $g(G) \subset G$. Hence $g(L) \subset L$. Let A and B be the two components of $L - \{0\}$; let e be the idempotent in A and f the idempotent in B. Now $(g(e))^2 = (xex)^2 = (xex)(xex) = xex = g(e)$ so g(e) is a (nonzero) idempotent in E. If g(e) = f then xex = f so xe = fx. But we have seen that $xA \cap Bx = \emptyset$ for all $x \in H(1)$ so this is impossible. Therefore xex = e. Similarly xfx = f. Thus g induces an involution on E with two fixed points so $E \subset F$. Since $E \subset F$ we infer from the above list of possibilities for $E \subset F$ that $E \subset F$. Hence $E \subset F$ and $E \subset F$.

PROPOSITION 5. Suppose $x \neq 0$, Px = xP and Px is a sub-semigroup of E. Then Px is a group isomorphic to P.

Proof. The proofs of Lemma 1.1 and Theorem 1.2 of [1] apply without change here to show that the map $t \rightarrow tx$ is a homeomorphism from P^- to P^-x (even more: for future reference we mention that P^-x is a closed subset of E). The same is true for the map $t \rightarrow xt$. Therefore for each $t \in P$ there is a unique element $h(t) \in P$ such that tx = xh(t). It is easy to see that h is a continuous function from P to itself and furthermore, since

$$(st)x = s(tx) = s(xh(t)) = (sx)h(t) = (xh(s))h(t)$$

and also

$$(st)x = xh(st),$$

we have h(st) = h(s)h(t) for all $s, t \in P$. Therefore there exists $u \in P$ such that $h(t) = t^u$; i.e. $tx = xt^u$ for all $t \in P$. Since $x^2 \in Px$ we have $x^2 = px$ for some $p \in P$. Now $xpx = x(xp^u) = x^2p^u = (px)p^u = p(xp^u) = p^2x$. Also, $xpx = (xp)x = (p^{1/u}x)$

 $=p^{1/u}x^2=p^{1/u}px$. Therefore $p^2x=p^{1/u}px$. Hence $p^2=p^{1/u}p$ so $p=p^{1/u}$. Thus, either p=1 and x is an idempotent or u=1. In the latter case tx=xt for all $t \in P$. In this case x/p is an idempotent. In any case, Px contains an idempotent e. Since Pe=Px and eP=xP, it follows that Pe=eP so e is an identity for Pe and hence Px. Thus Px is a semigroup with identity and no other idempotents so Px is a group isomorphic to P.

PROPOSITION 6. Suppose $G^-=P^-\times P^-$. Then 1 has at least three square roots if and only if H(1) has at least three components. In either case, 1 has exactly four square roots, H(1) has exactly four components and H(1) is the product of G and the four group. In particular, H(1) is commutative.

Proof. If $x \neq y$ and $x^2 = y^2 = 1$ then $xG \neq yG$. Therefore if 1 has at least three square roots then H(1) has at least three components. The converse is an immediate consequence of Proposition 3.

Now suppose 1 has at least three square roots. By Proposition 4, if $x^2 = 1$ then x is in the center of G. The knowledge that if $x^2 = 1$ then xy = yx for $y \in E$ is all that is needed to make the argument given in [1] applicable under the present circumstances to show that H(1) has exactly four components. Of course each component contains a square root of 1 so the remainder of the proposition follows immediately.

PROPOSITION 7. Assume $G^- = P^- \times P^-$. Let x_1, x_2, x_3 and 1 be distinct square roots of 1. Let the fixed point set of the mapping $x \to xx_i$ be denoted F_i for i = 1, 2, 3. Then we may assume the x_i numbered so that F_1 and F_3 are (closed) semigroups isomorphic to R and $F_1 \cap F_3 = F_2 = \{0\}$.

Proof. Let $V = \{x_1, x_2, x_3, 1\}$. Then V is the four group which obviously acts effectively on E. It is well known such an action is equivalent to the ordinary action. (See [8], for example.) Therefore, two of the fixed-point sets are closed lines and the third is the point of intersection of these two. There is no harm in labeling the first two F_1 and F_3 and the third F_2 . Since x_1 is in the center of E, F_1 is an ideal in E and in particular a sub-semigroup of E. A corresponding statement holds for F_3 . Since $F_1 \cap F_3 = F_2$ and F_2 is an ideal containing but one point, $F_2 = \{0\}$.

Now multiplication by x_1 reflects E about F_1 , so F_1 separates G and x_1G . We now use the notation and language developed just prior to Proposition 3. Suppose x_i is the member of V such that x_iG is the first component of H(1) after G. Then $x_iD_0 \subset D_0$. There are now two possibilities. Either D_0 is one of the components of $L - \{0\}$ or the interior of D_0 is a plane. In either case, since $x_iD_0 \subset D_0$ and an involution on a plane or a line has at least one fixed point, D_0 contains a nonzero fixed point under multiplication by x_i . Thus either F_1 or F_3 passes through D_0 . There is nothing lost in assuming it is F_1 . Let $x \in F_1 \cap D_0$. Certainly $GD_0 \subset D_0$ and $D_0G \subset D_0$ so $Px \subset D_0$ and $xP \subset D_0$. Since F_1 is an ideal, Px and xP are contained in F_1 . As we know,

 P^-x is a closed homeomorph of P^- so since F_1 is a line, Px = xP. It is clearly impossible for $F_1 \cap D_0$ to contain points outside Px. Since $x^2 \in F_1 \cap D_0$, $x^2 \in Px$. Since Px = xP this implies Px is a sub-semigroup of E. By Proposition 5, Px is a group isomorphic to P. That F_1 is isomorphic to P now follows easily since P induces a reflection on P whose only fixed point is 0. The argument for P is similar so the proof of the proposition is complete.

Proof of the Main Theorem. We prove $(2)\Rightarrow(3)\Rightarrow(1)$. It is obvious that $(1)\Rightarrow(2)$.

Assume (2); according to Proposition 6, 1 has four square roots and H(1) has exactly four components. Thus we have the second part of (3). Now denote the square roots of 1 by 1, x_1 , x_2 and x_3 and denote the fixed-point set of the mapping $x \rightarrow xx_i$ by F_i for i = 1, 2, 3. By Proposition 7 we may suppose F_1 and F_2 are ideals in E, each isomorphic to E and E and E are ideals in E, each isomorphic to E and E are ideals in E, each isomorphic to E and E are ideals in E as four idempotents E as only four idempotents there are distinct nonzero idempotents. If E has only four idempotents then E and E are ideals in E and idempotents. If E has only four idempotents then E and E are ideals of E and E are ideals in E and idempotents. If E has only four idempotents then E and E are ideals of E and idempotents. If E has only four idempotents then E and identify E are ideals of E and identify E are ideals of E and identify E are ideals in E and identify E and identify E are ideals in E and we have that E and identify E and E are ideals of E and identify E and E are ideals of E and identify E and identify E are ideals in E and we have that E and identify E and E are ideals in E and we have that E and identify E and E are ideals in E and identify E and identify E are ideals in E and identify E and identify E are ideals in E and identify E are ideals and identify E are ideals in E and identify E and identify E are ideals in E and identify E and identify E are ideals in E and identify E and identify E are ideals in E and identify E are ideals and identified in E and identify E are ideals in E and identify E and identified in E and identi

Now assume (3). Then $G^-=P^-\times P^-$ so by Proposition 6, 1 has exactly four square roots and H(1) is a commutative group. Since H(1) is dense in E, E is a commutative semigroup. Also, according to Proposition 7, we can choose an element x_2 so that $(x_2)^2=1$ and $x\neq 0$ implies $x_2x\neq x$. It is now straightforward to prove $E=R\times R$. Alternately, observe that $P^-\cup Px_2$ is a semigroup through the zero and identity of E which is isomorphic to E. Therefore E is a real commutative semigroup. With E0 playing the role of E1 we see that E1.

Two final remarks are in order. First, examples in [1] show that it is not possible to assume fewer than three square roots of the identity in (2), nor fewer than three components for H(1) in (3) without making the theorem false.

Second, in virtue of Proposition 6, a certain amount of mixing of the hypotheses in (2) and (3) is possible without affecting the validity of the theorem. Specifically, the assumption concerning idempotents in (2) is interchangeable with the assumption concerning the denseness of H(1) in (3). Furthermore, the hypothesis concerning square roots of 1 in (2) is interchangeable with that concerning components of H(1) in (3). For after an interchange of the first sort we can still conclude that $G^- = P^- \times P^-$. Therefore Proposition 6 is applicable so the assumption concerning square roots is

seen to be equivalent to the assumption concerning the number of components of H(1).

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